

Notes and errata of the paper:

## Grayscale Template-Matching Invariant to Rotation, Scale, Translation, Brightness and Contrast

Hae Yong Kim and Sidnei Alves de Araújo

**Question 1:** Can Cifi and Rafi be exchanged? That is, is it possible to do Rafi first, and then do Cifi?

**Question 2:** I implemented Ciratefi as described in your paper. Why my implementation does not find small templates, while the implementation I downloaded from your homepage does?

**Answer to both questions:** There is a detail about Cifi that we forgot to explain in the paper. I will explain it through an example. Let us suppose that Cifi has computed 5 circular projections for each pixel of the image to analyze  $A$ . Let  $Q_{1.2}$ ,  $Q_{1.0}$  and  $Q_{0.8}$  be the query template  $Q$  scaled by factors 1.2, 1.0, and 0.8 (note that  $Q = Q_{1.0}$ ). Let us suppose that 6 circles fit inside  $Q_{1.2}$ , 5 circles fit inside  $Q_{1.0}$  and 4 inside  $Q_{0.8}$ . Then, Cifi uses all 5 circles of  $Q_{1.0}$  to find  $Q_{1.0}$  in  $A$ . It ignores the outermost circle of  $Q_{1.2}$ , using only the 5 inner circles to find it. And it uses only 4 circles of  $Q_{0.8}$  (it ignores the outermost circle or, equivalently, inserts a dummy “don’t care” outermost circle) to find  $Q_{0.8}$ .

**Answer to Question 1:** No, Cifi cannot be exchanged with Rafi. Using Rafi first, it is impossible to insert a dummy “don’t care” circle. Moreover, it is not possible to run Rafi without the “probable scale factor” computed by Cifi.

**Answer to Question 2:** You must implement Cifi’s “normalized cross correlation” taking into account the property explained above.

### Errata:

The correct equation (5) is:

$$\text{Cis}_B(x, y, r) = \frac{1}{2\pi r} \int_0^{2\pi} B(x + r \cos \theta, y + r \sin \theta) d\theta \quad (5)$$

The correct equation (10) is:

$$\text{Ras}_B^\lambda(x, y, \alpha) = \frac{1}{\lambda} \int_0^\lambda B(x + t \cos \alpha, y + t \sin \alpha) dt \quad (10)$$